

# Introduction to SAR Polarimetry

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29 November 2017



# Acknowledgements

From NASA:

- Bruce Chapman
- Michael Denbina
- Scott Hensley
- Marco Lavalle
- Yunling Lou
- Marc Simard
- UAVSAR team
- Armstrong Flight Research Center

From Alaska Satellite Facility:

- Brian Huberty

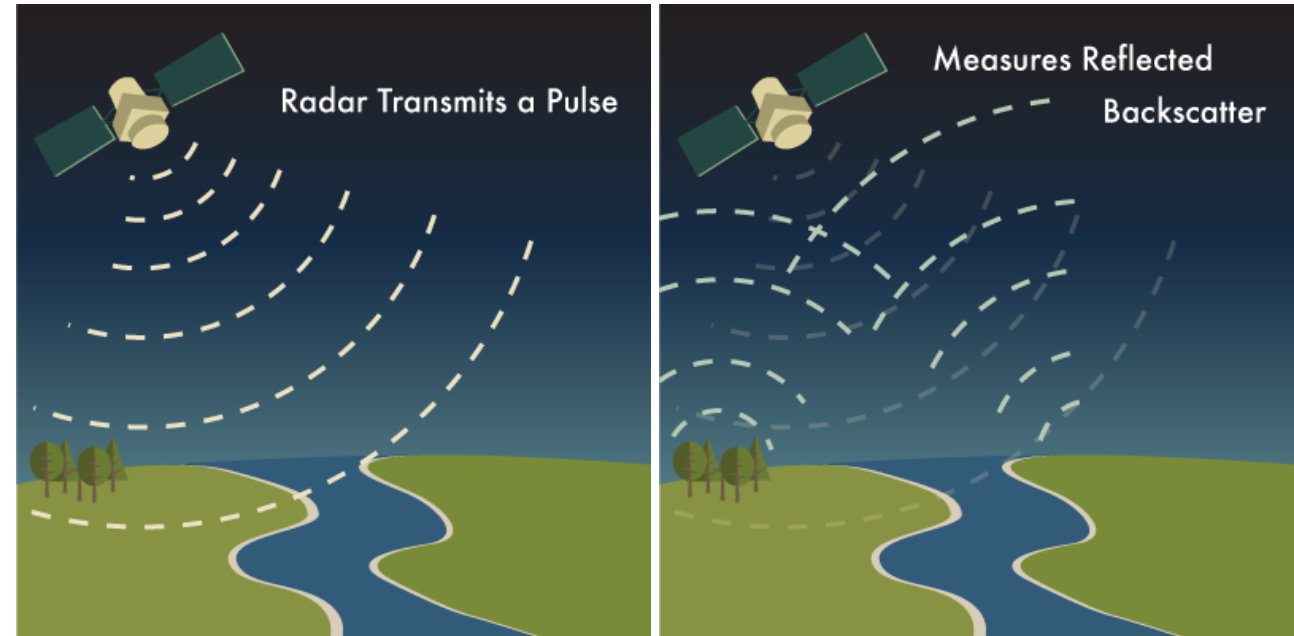




# Learning Objectives

- The received radar signal provides information about properties of scatterers on the ground
- More information is gained by studying different polarizations
- Our objective is to provide a brief introduction to polarimetry and familiarize students with:
  - Mathematical representation
  - Data format
  - Data processing for land cover mapping

Source: ESA- ASAR Handbook





# Outline

1. Why polarimetry?
2. Polarization
3. Scattering mechanisms
4. Data and software
5. Processing Sentinel-1 dual-pol images
6. Processing UAVSAR quad-pol images
7. Display the results





Why Polarimetry?



# Optical Imagery: Libreville, Gabon,



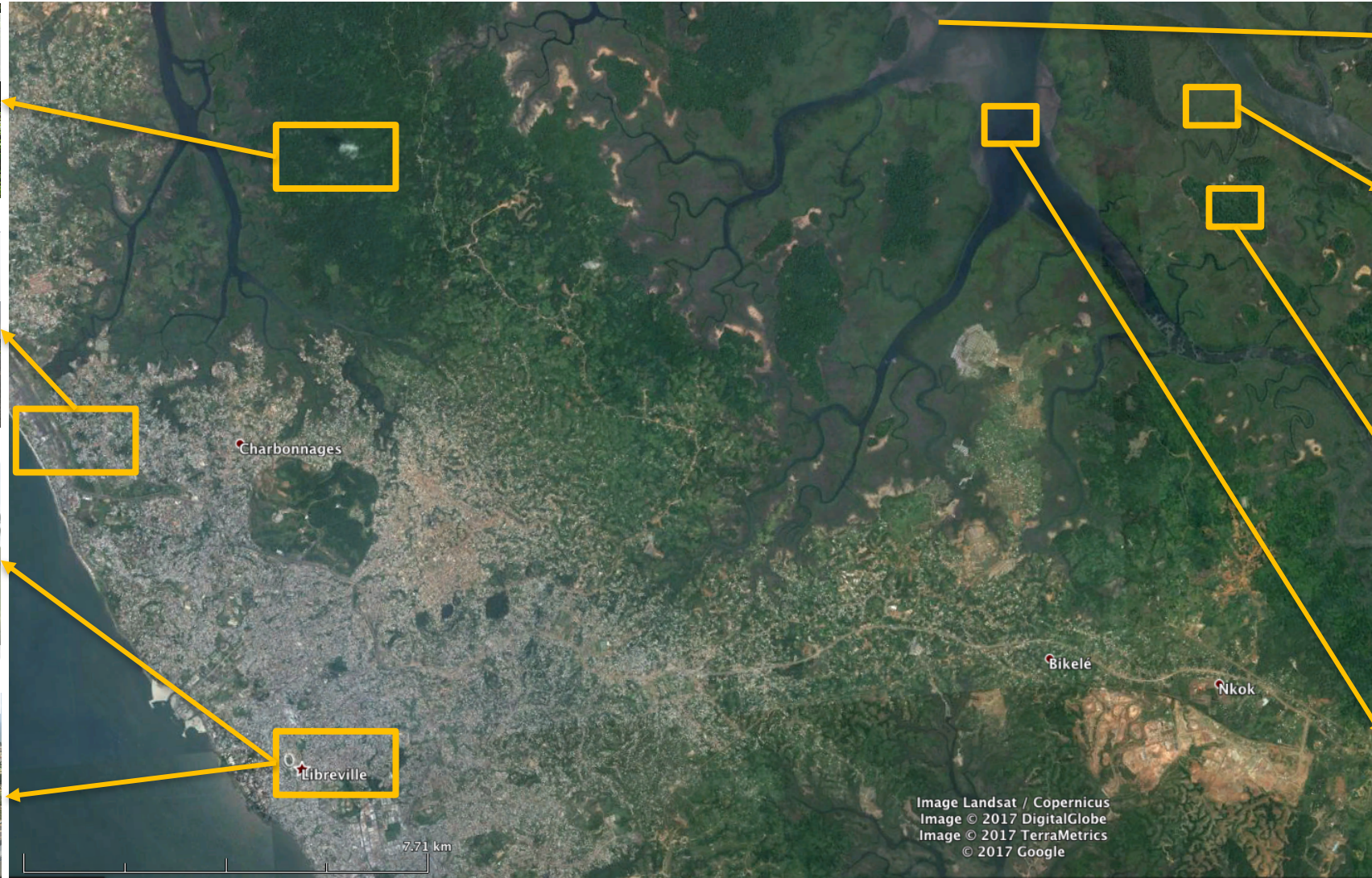
forest



runway



buildings



mud banks



dense mangrove



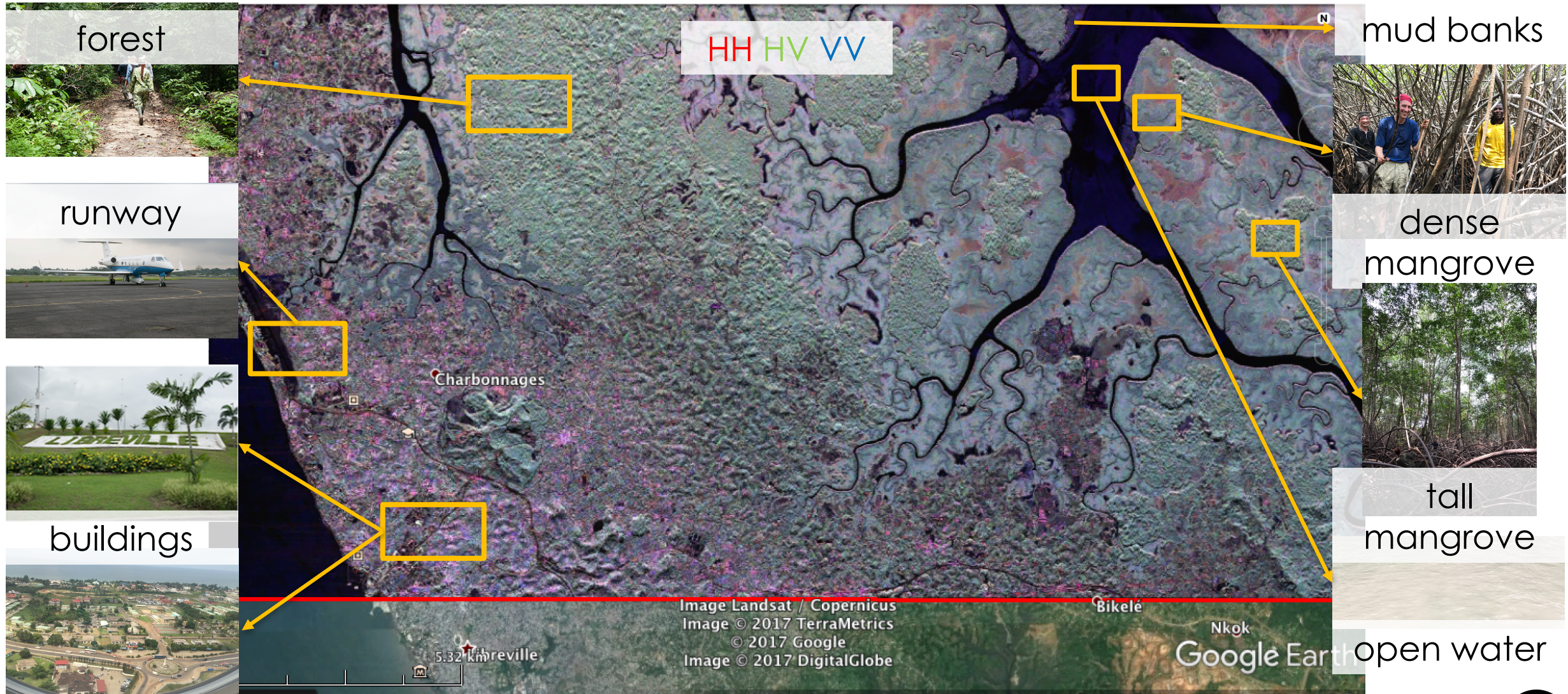
tall mangrove



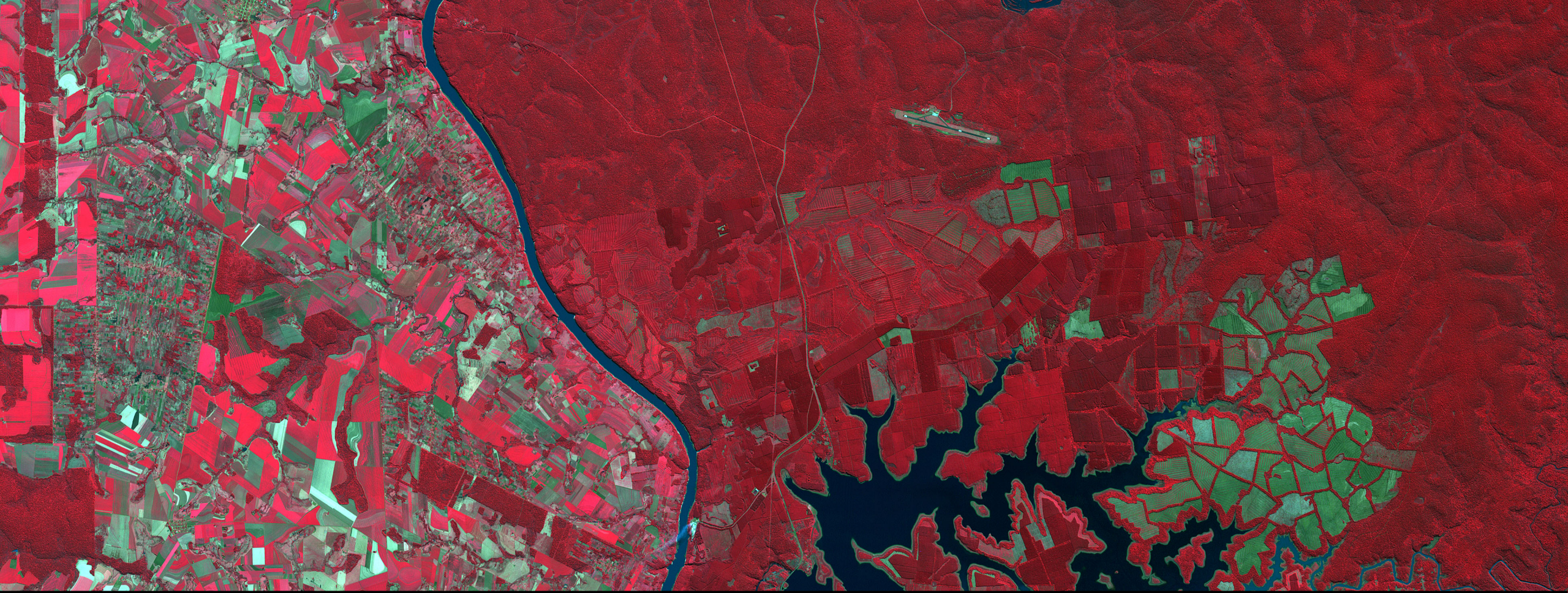
open water



# L-Band SAR Imagery: Libreville, Gabon,





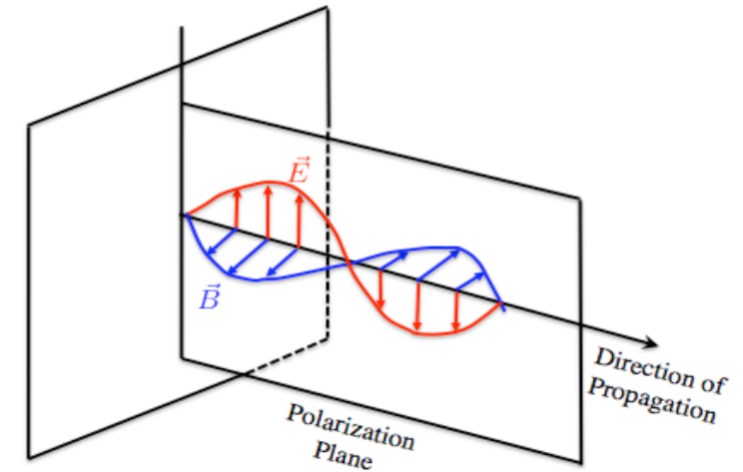


Polarization



# Polarization

- Radars produce electromagnetic waves. The direction of the electric field lies in the plane perpendicular to the direction of propagation and defines the polarization of the wave.
- Dual-pol instruments:
  - Transmit H or V, receive H and V simultaneously
- Quad-pol instruments:
  - Transmit H and V on alternate pulses, receive H and V simultaneously
- The amount of returned signal for different polarizations depends on the physics of the interaction of microwaves with the surface



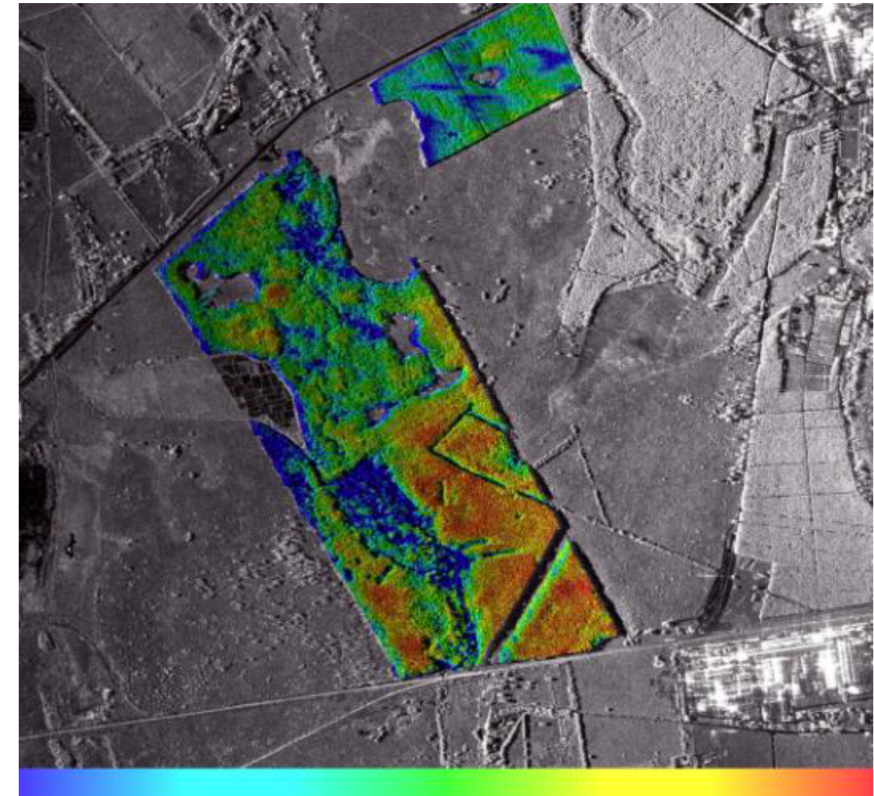
		transmit	
		H	V
receive	H	HH	VH
	V	HV	VV



# Polarimetry

- The study of using multiple polarimetric returns to infer information about a surface
- Applications include:
  - Cryosphere
  - Vegetation
  - Hydrology

## Vegetation Volume in Southeast Brazil



0 m<sup>3</sup>/ha

325 m<sup>3</sup>/ha

Gama, F. F., Santos, J. R., & Mura, J. C. (2010). Eucalyptus Biomass and Volume Estimation Using Interferometric and Polarimetric SAR Data. *Remote Sensing*, 2(4), 939-956.  
doi:10.3390/rs2040939

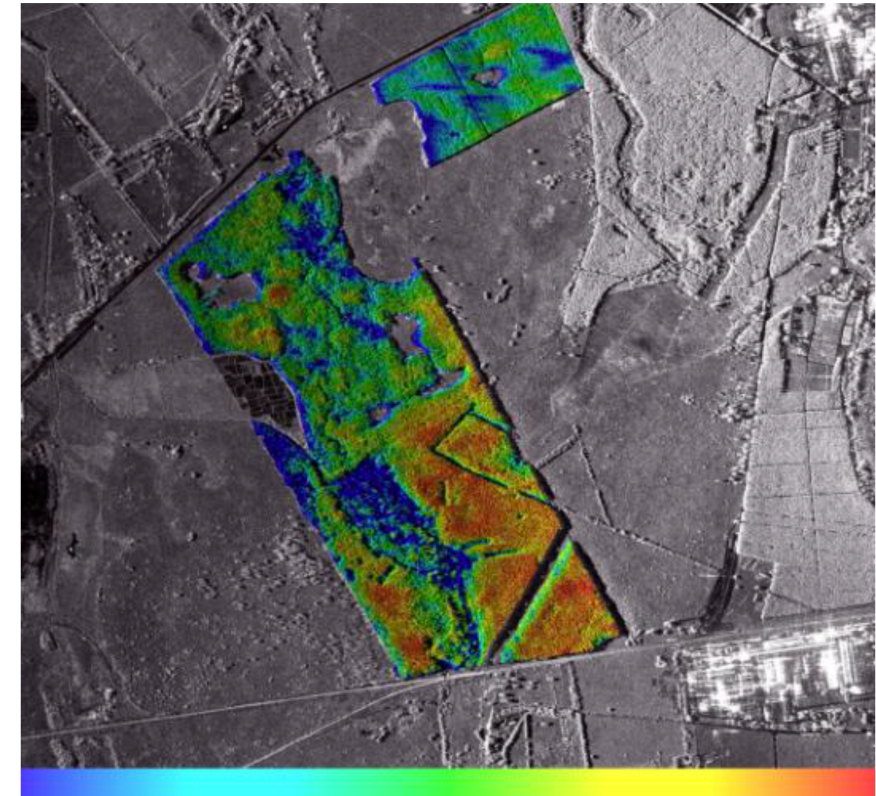




# Polarimetry

- Two complementary approaches to studying polarimetry:
  - Theoretical models predict how polarized signal interacts with different media
  - Observations made with remote sensing instruments reveal polarization signatures for a range of land cover types

## Vegetation Volume in Southeast Brazil



0 m<sup>3</sup>/ha

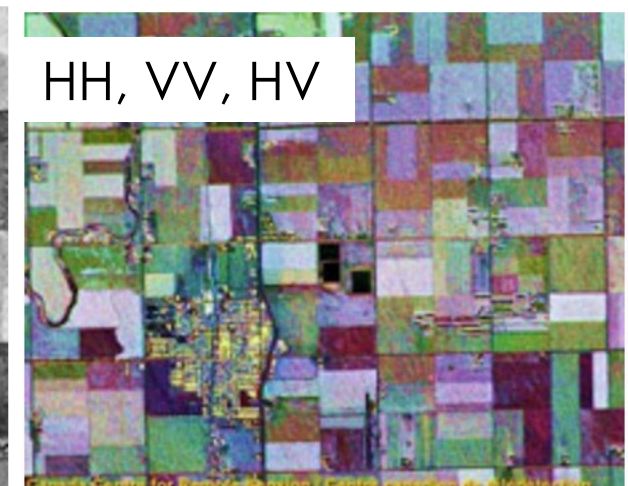
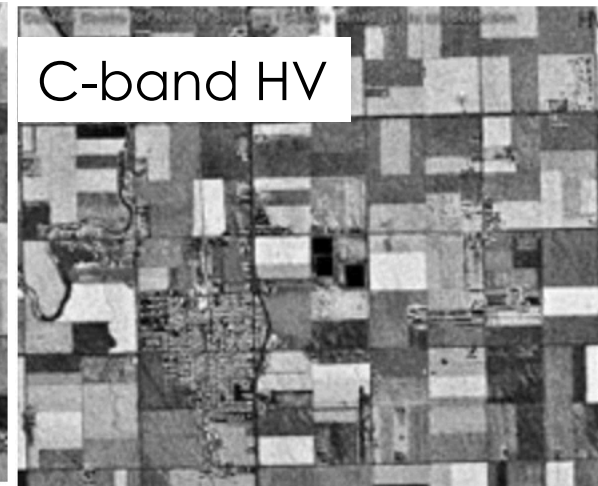
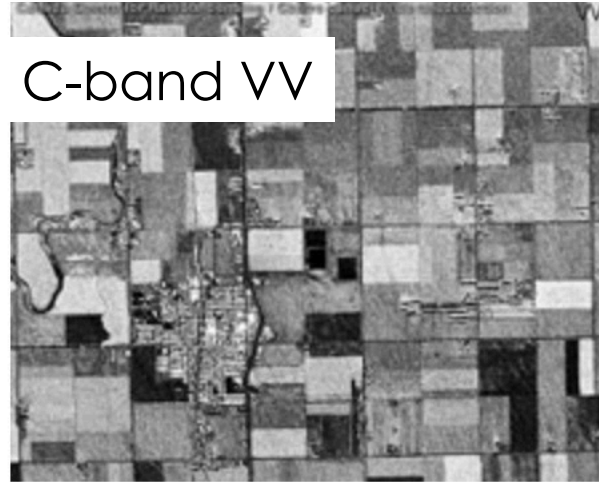
325 m<sup>3</sup>/ha

Gama, F. F., Santos, J. R., & Mura, J. C. (2010). Eucalyptus Biomass and Volume Estimation Using Interferometric and Polarimetric SAR Data. *Remote Sensing*, 2(4), 939-956.  
doi:10.3390/rs2040939





# Multiple Polarizations







# Scattering Mechanisms

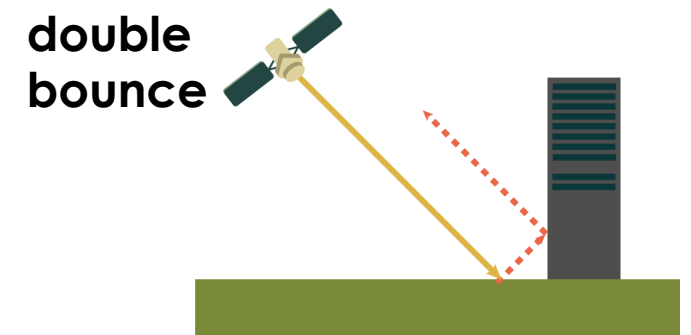
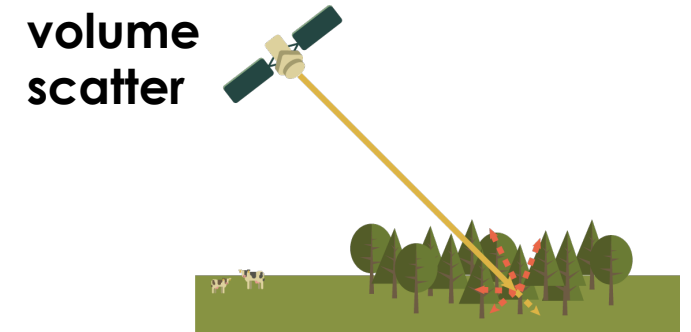
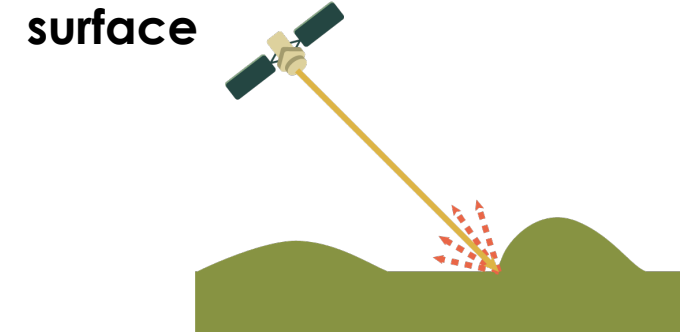


# Scattering Mechanisms

- Quantifying scattering mechanisms starts by encoding the received radar signal in a scattering matrix
- In the quad pol scenario, we can represent the received signal with a 3x3 T3 coherency matrix:

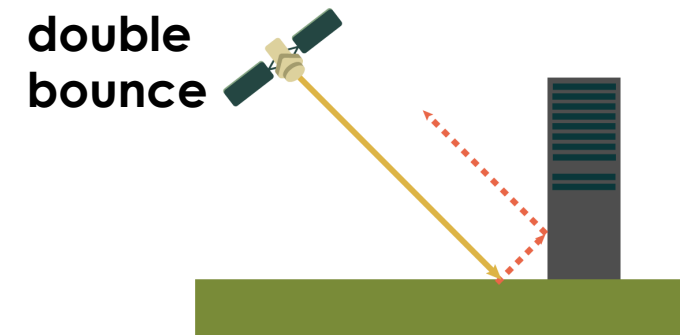
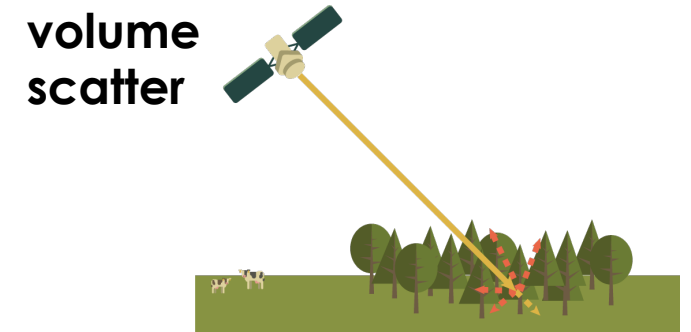
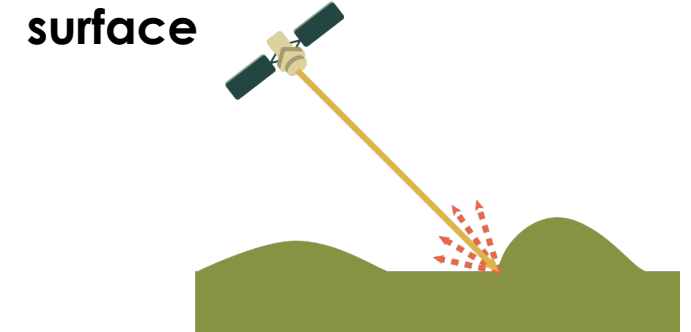
$$[T] = \frac{1}{2} \begin{bmatrix} \langle |S_{HH} + S_{VV}|^2 \rangle & \langle (S_{HH} + S_{VV})(S_{HH} - S_{VV})^* \rangle & 2\langle (S_{HH} + S_{VV})S_{HV}^* \rangle \\ \langle (S_{HH} - S_{VV})(S_{HH} + S_{VV})^* \rangle & \langle |S_{HH} - S_{VV}|^2 \rangle & 2\langle (S_{HH} - S_{VV})S_{HV}^* \rangle \\ 2\langle S_{HV}(S_{HH} + S_{VV})^* \rangle & 2\langle S_{HV}(S_{HH} - S_{VV})^* \rangle & 4\langle |S_{HV}|^2 \rangle \end{bmatrix}$$

- \* denotes conjugation and < > denotes averaging



# Scattering Mechanisms

- All 9 elements in the T matrix are calculated for each pixel in your image.
- We employ polarimetric decompositions to obtain a small set of parameters to classify scattering mechanisms





# H- $\alpha$ Decomposition

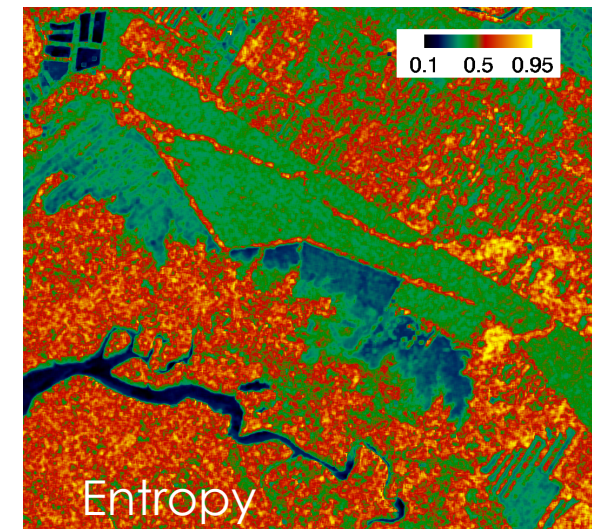
- Based on eigenvalue / eigenvector decomposition of the T3 matrix

$$[T] = [U_3] \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} [U_3]^*{}^T$$

$$[U_3] = \begin{bmatrix} \cos \alpha_1 & \cos \alpha_2 & \cos \alpha_3 \\ \sin \alpha_1 \cos \beta_1 e^{i\delta_1} & \sin \alpha_2 \cos \beta_2 e^{i\delta_2} & \sin \alpha_3 \cos \beta_3 e^{i\delta_3} \\ \sin \alpha_1 \sin \beta_1 e^{i\gamma_1} & \sin \alpha_2 \sin \beta_2 e^{i\gamma_2} & \sin \alpha_3 \sin \beta_3 e^{i\gamma_3} \end{bmatrix}$$

- Eigenvalues are used to calculate entropy (H), which is a function of noise owing to depolarization

$$\text{entropy: } H = \sum_{i=1}^3 p_i \log_3 p_i \quad 0 \leq H \leq 1 \quad p_i = \frac{\lambda_i}{\sum_{q=1}^3 \lambda_q}$$



# H- $\alpha$ Decomposition

- Based on eigenvalue / eigenvector decomposition of the T3 matrix

$$[T] = [U_3] \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} [U_3]^*{}^T$$

$$[U_3] = \begin{bmatrix} \cos \alpha_1 & \cos \alpha_2 & \cos \alpha_3 \\ \sin \alpha_1 \cos \beta_1 e^{i\delta_1} & \sin \alpha_2 \cos \beta_2 e^{i\delta_2} & \sin \alpha_3 \cos \beta_3 e^{i\delta_3} \\ \sin \alpha_1 \sin \beta_1 e^{i\gamma_1} & \sin \alpha_2 \sin \beta_2 e^{i\gamma_2} & \sin \alpha_3 \sin \beta_3 e^{i\gamma_3} \end{bmatrix}$$

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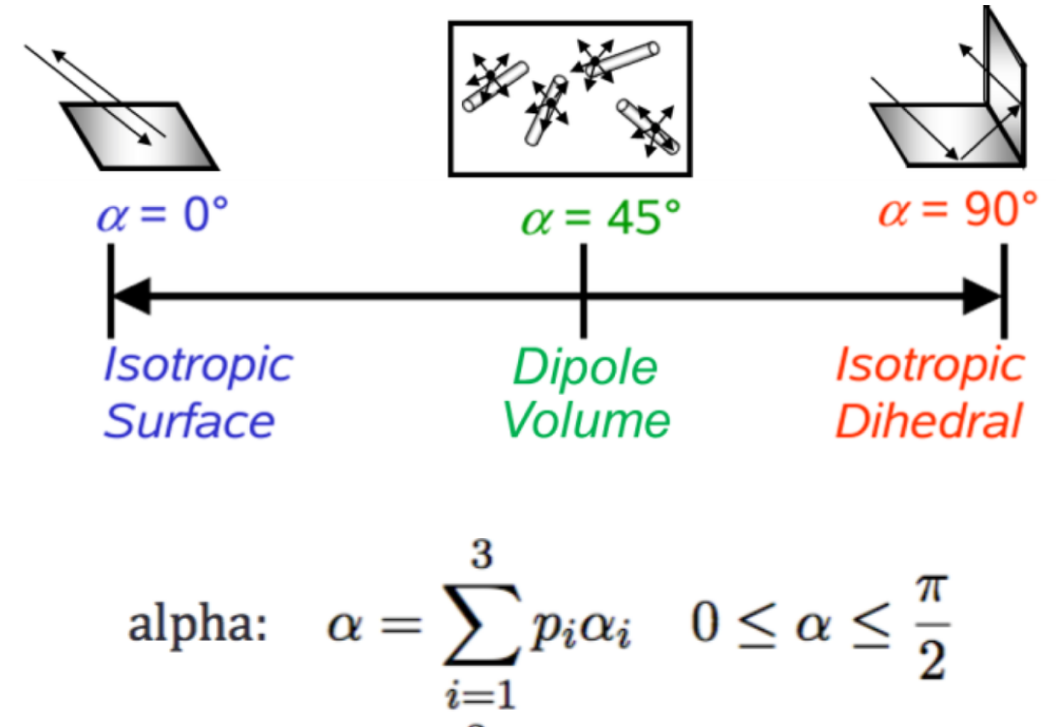
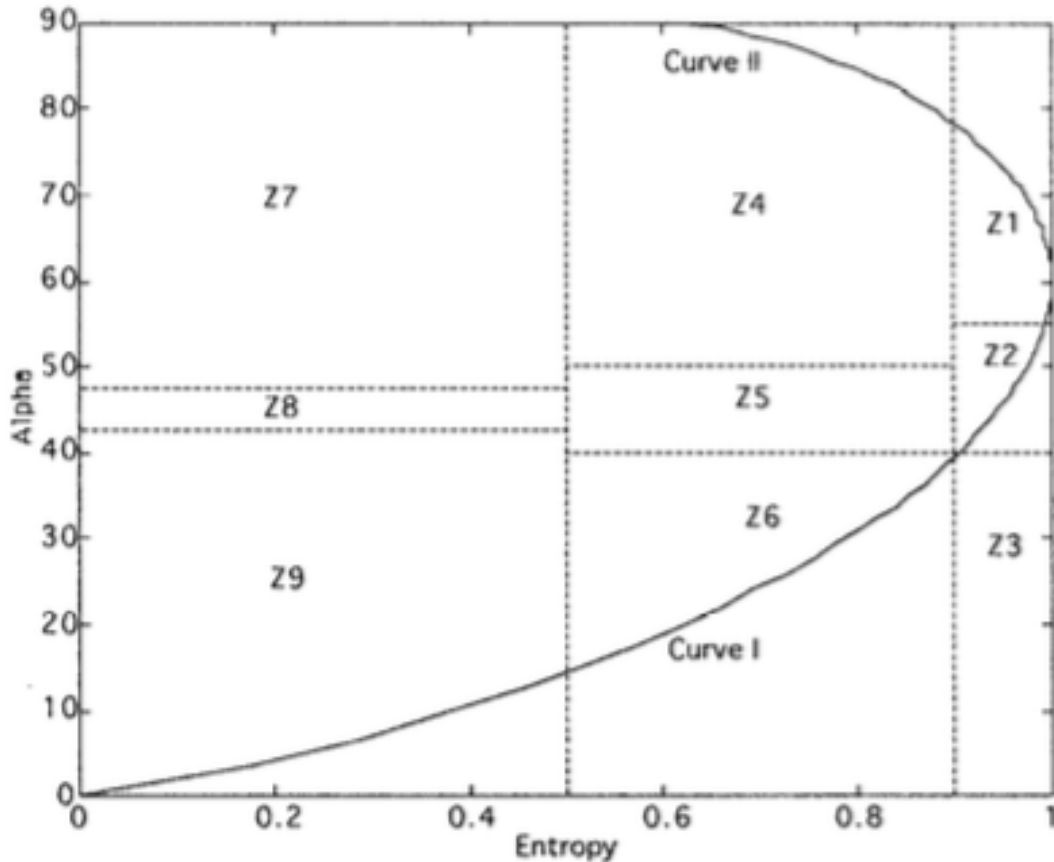


Figure from Jagdhuber, Thomas, et al. "Identification of soil freezing and thawing states using SAR polarimetry at C-Band." *Remote Sensing* 6.3 (2014): 2008-2023.





# H- $\alpha$ Classification



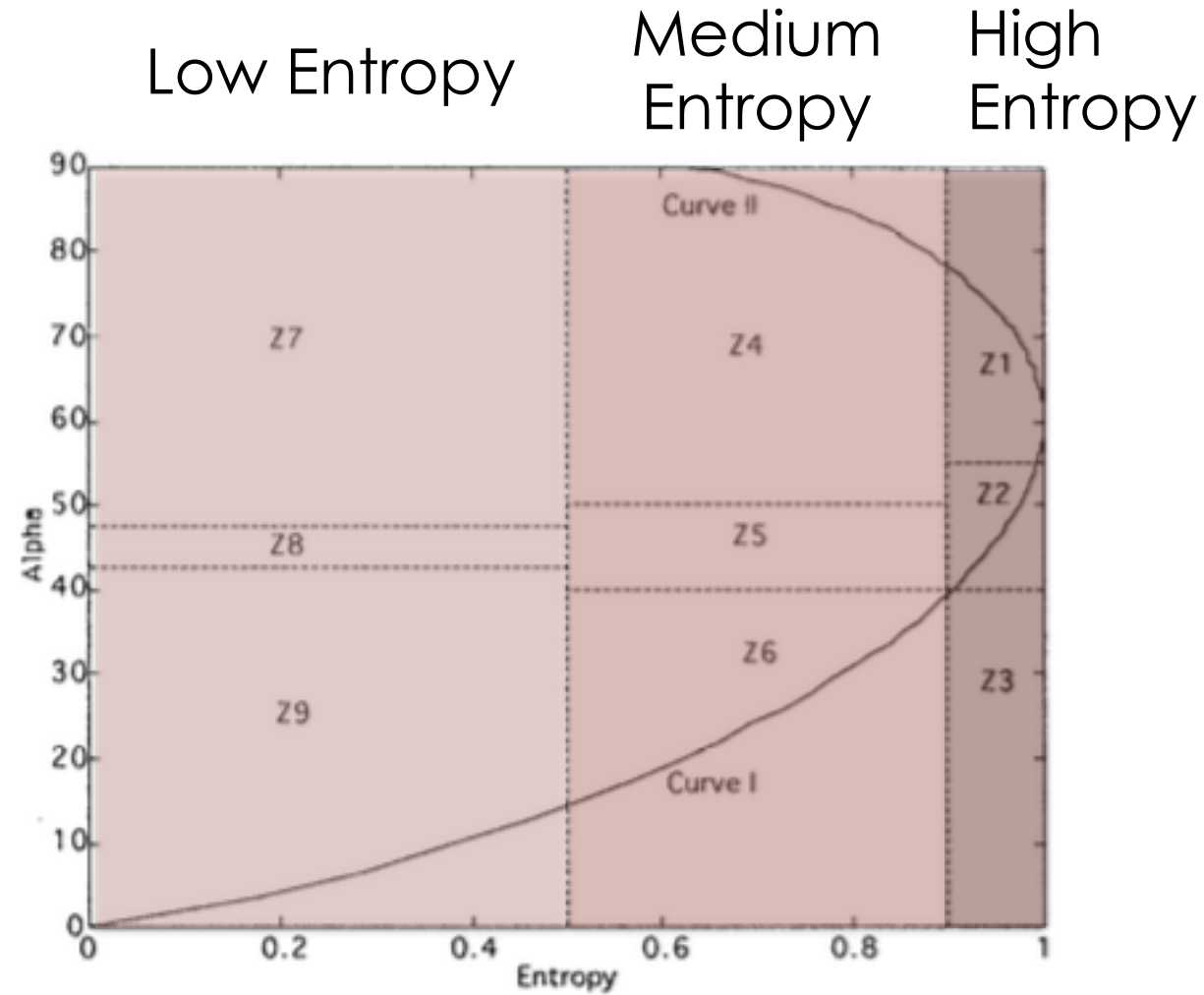
Feasible region in  $\alpha$ -H plane for random media scattering problems.

Cloude, Shane R., and Eric Pottier. "An entropy based classification scheme for land applications of polarimetric SAR." *IEEE Transactions on Geoscience and Remote Sensing* 35.1 (1997): 68-78.

- Two-parameter system used to classify different types of scattering behavior
- 9 Zones
- Results from this unsupervised classification can be combined with other layers and used as inputs for a supervised classifier.
- For example: Qi, Zhixin, et al. "A novel algorithm for land use and land cover classification using RADARSAT-2 polarimetric SAR data." *Remote Sensing of Environment* 118 (2012): 21-39.



# H- $\alpha$ Classification



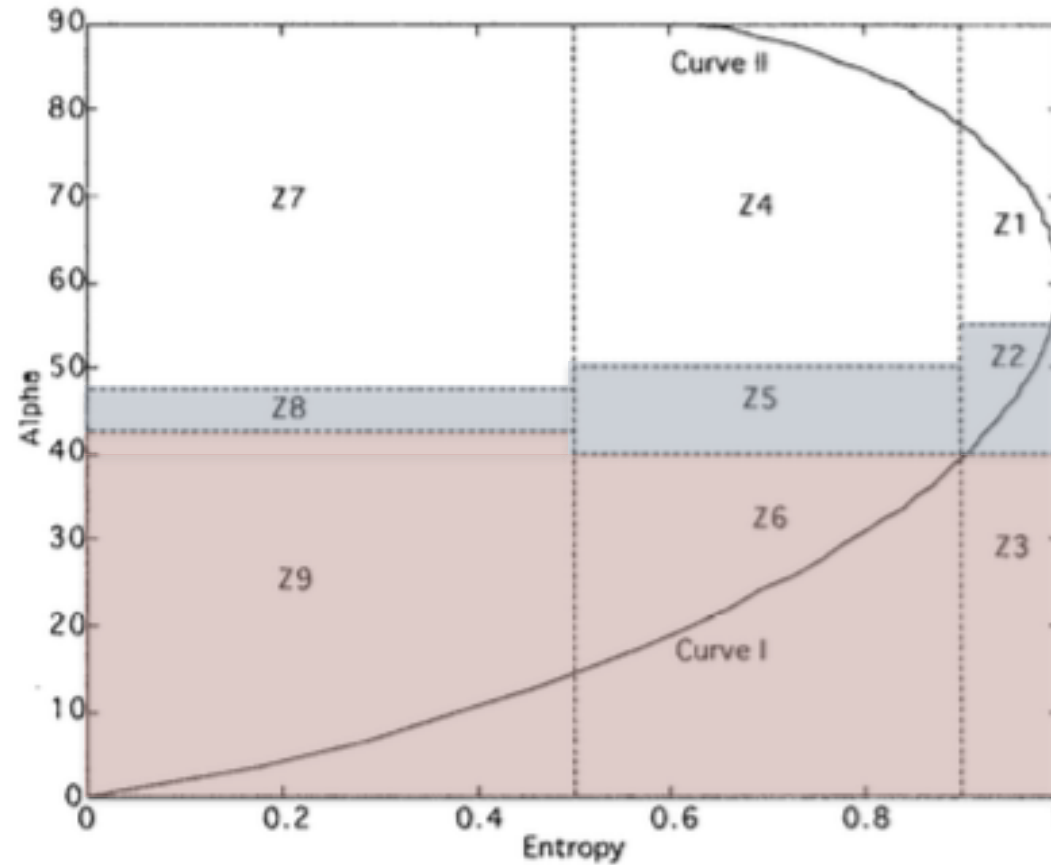
Cloude, Shane R., and Eric Pottier. "An entropy based classification scheme for land applications of polarimetric SAR." *IEEE Transactions on Geoscience and Remote Sensing* 35.1 (1997): 68-78.





# H- $\alpha$ Classification

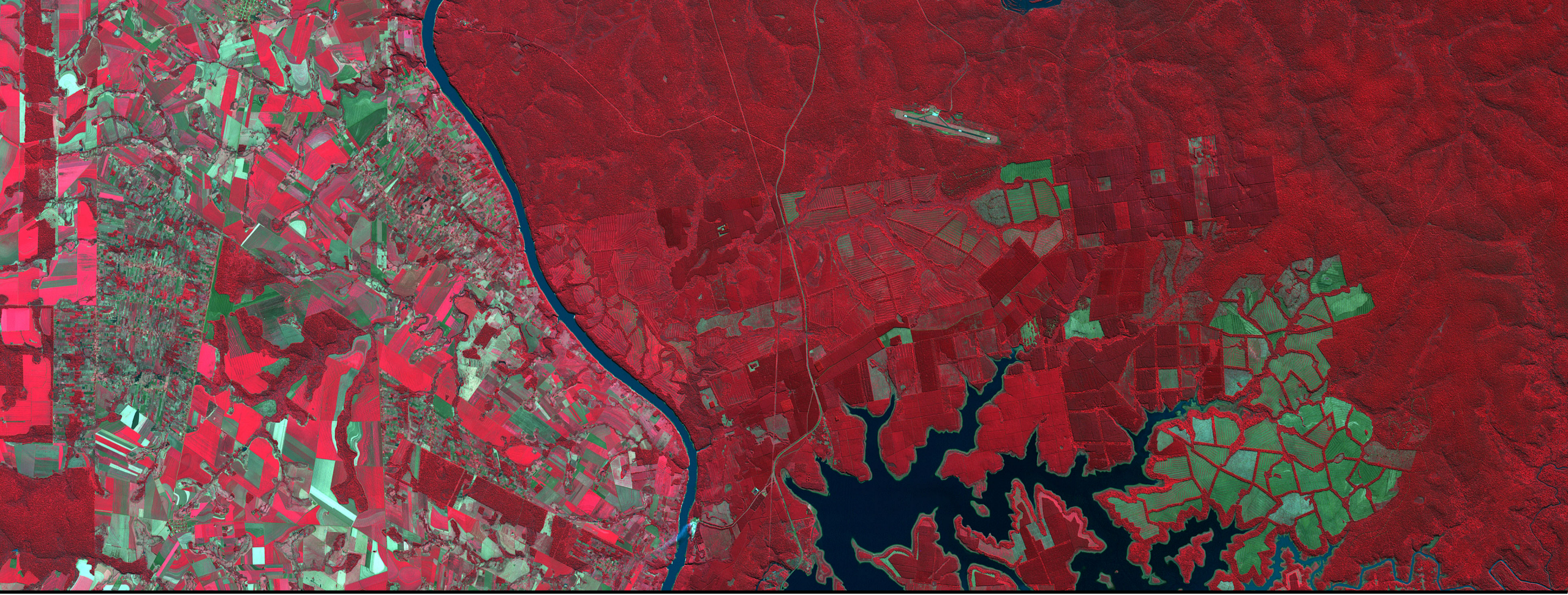
Multiple  
Dipole /  
Vegetation  
Surface



Cloude, Shane R., and Eric Pottier. "An entropy based classification scheme for land applications of polarimetric SAR." *IEEE Transactions on Geoscience and Remote Sensing* 35.1 (1997): 68-78.





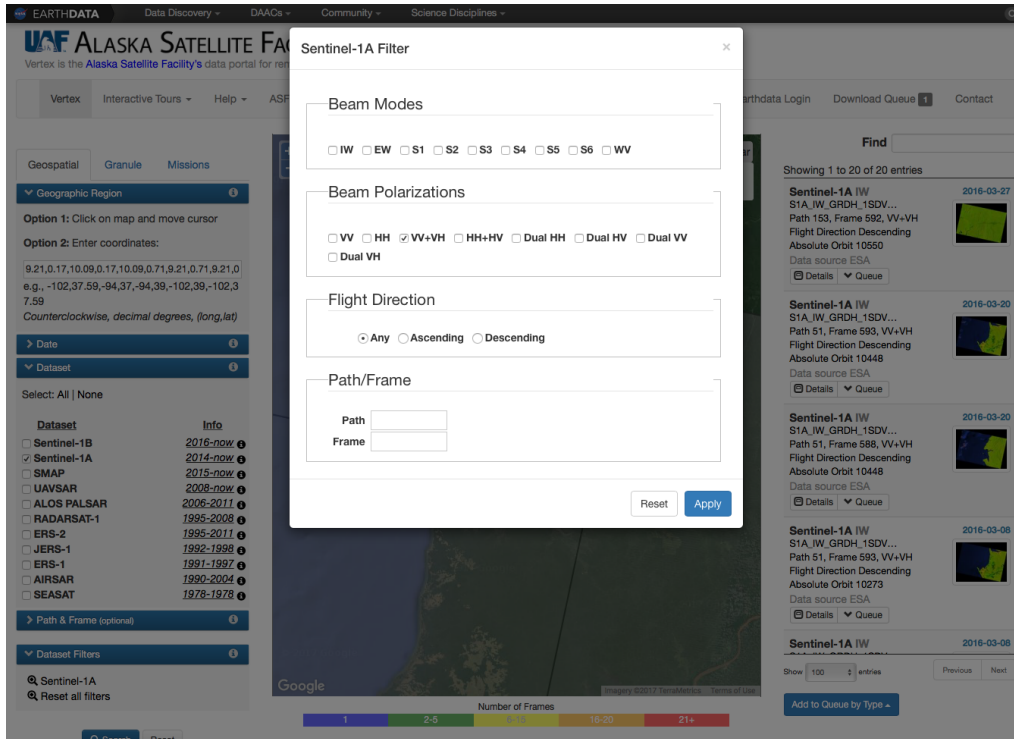


Processing Sentinel-1 Data



# Sentinel-1 Download from the Alaska Satellite Facility

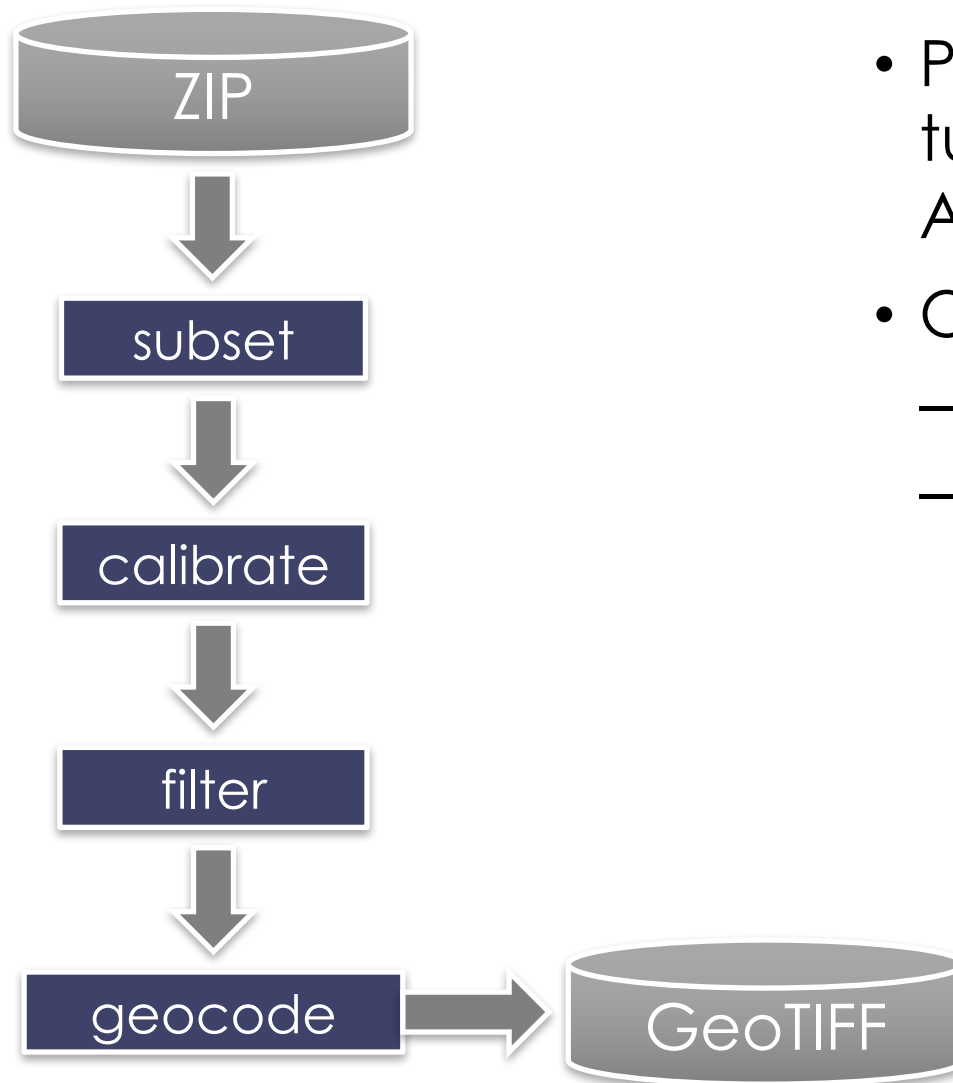
<https://vertex.daac.asf.alaska.edu/>



- Spaceborne instrument operated by ESA
- C band (5-cm wavelength)
- Two polarizations:
  - VH, VV
- GRD (Ground Range Detected) product
- 10 meters spatial posting
- Product ID:
  - S1A\_IW\_GRDH\_1SDV\_20160320T050613\_20160320T050638\_010448\_00F805\_14D5
- Acquired on March 20, 2016
- Download the zip file



# Sentinel-1 Process in SNAP



- Process following the steps in the tutorial “SAR Processing and Data Analysis”
- Outputs two files:
  - VV
  - VH







Processing UAVSAR



# Uninhabited Aerial Synthetic Aperture Radar (UAVSAR)

<https://uavsar.jpl.nasa.gov>

NASA Jet Propulsion Laboratory  
California Institute of Technology

JPL HOME EARTH SOLAR

## UAVSAR Data Search ?

[ Hide ]

**Date range**

to

☐ All flown data (admin only, KMLs may be missing)  
includes non-released products (but no stacks)

**Processing modes ?**

☒ PolSAR  
☐ InSAR Pair  
☐ InSAR Browse  
☐ SLC Stack  
☐ TomoSAR  
☐ TopSAR (Ka-band)

**Band ?**

☒ L-band  
☐ P-band  
☐ Ka-band

**Find** (line name/description, product ID, flight ID, SOFRS ID, or deployment name) ?

Lat: Lng: ☐ Show

Zoom in to click on a flight line

Map

14,690 products from

- ▶ Aguatc\_03901 (
- ▶ Aguatc\_31602 (
- ▶ aistSN\_15002 (
- ▶ aistSN\_33001 (
- ▶ alaska\_13047 (

- Airborne instrument operated by NASA
- L band (24-cm wavelength)
- Fully polarimetric
- GRD (Ground Range Detected) product
- 6 meters posting





# Uninhabited Aerial Synthetic Aperture Radar (UAVSAR)

<https://uavsar.jpl.nasa.gov>

## Precision Data

The NASA data archive at ASF now requires login. If you do not have an account, any user c

Metadata Text Annotation File

Slant Range Products ShhShh\* (0.1431 Gbytes)  
ShvShv\* (0.1431 Gbytes)  
SvvSvv\* (0.1431 Gbytes)  
ShhShv\* (0.2861 Gbytes)  
ShhSvv\* (0.2861 Gbytes)  
ShvSvv\* (0.2861 Gbytes)  
Compressed Stokes Matrix (AIRSAR format) (0.3578 Gbytes)

Orthorectified Products (geographic projection) ShhShh\* (0.1893 Gbytes)  
ShvShv\* (0.1893 Gbytes)  
SvvSvv\* (0.1893 Gbytes)  
ShhShv\* (0.3785 Gbytes)  
ShhSvv\* (0.3785 Gbytes)  
ShvSvv\* (0.3785 Gbytes)  
High Resolution KMZ file (0.1800 Gbytes)

SRTM DEM Incidence Angle File (0.1893 Gbytes)  
SLOPE File (0.3785 Gbytes)  
DEM used in projection (0.1893 Gbytes)

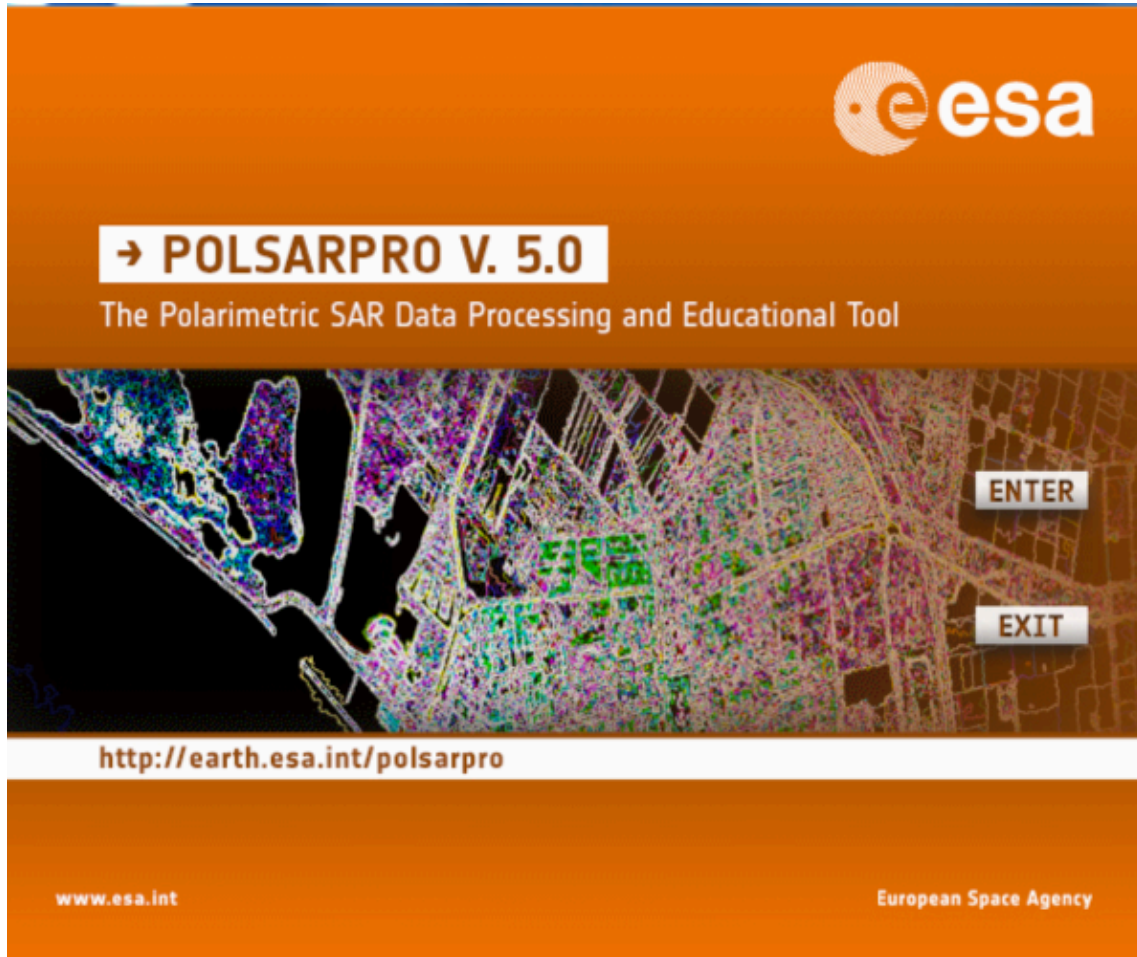
[Data Format Documentation](#)

- Product ID:
  - Mondah\_27080\_16015\_000\_160308\_L090\_CX\_02
- Acquired on March 03, 2016
- Download all 6 \*.GRD files as well as annotation file \*.ANN



# PolSARpro

<https://earth.esa.int/web/polsarpro/download/version-5.0>



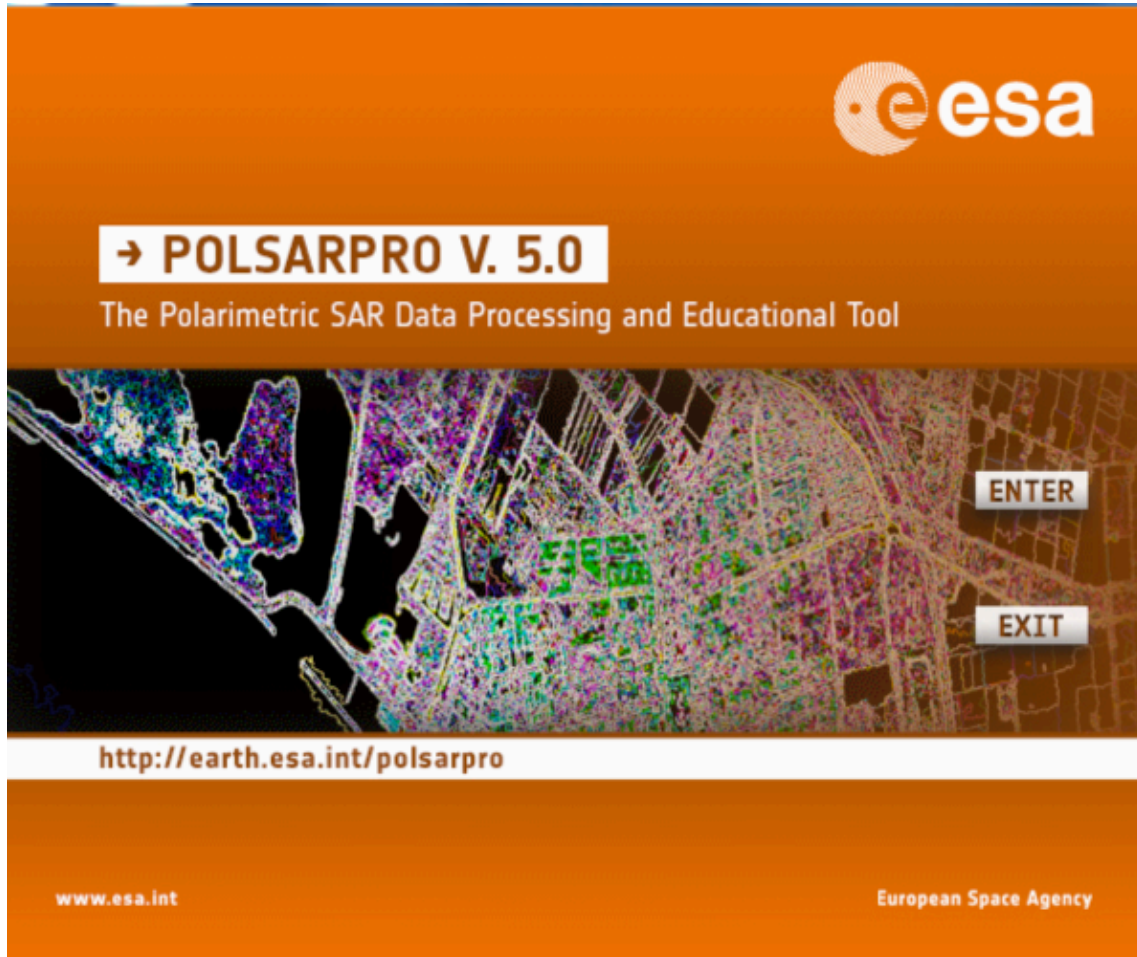
- PolSARpro is developed under contract with ESA since 2003. The IETR (Institute of Electronics and Telecommunications of Rennes - UMR CNRS 6164) of the University of Rennes 1, France is in charge of the development of the PolSARpro software.
- Windows and Linux; it is possible to compile on MacOSX from Linux source files





# PolSARpro

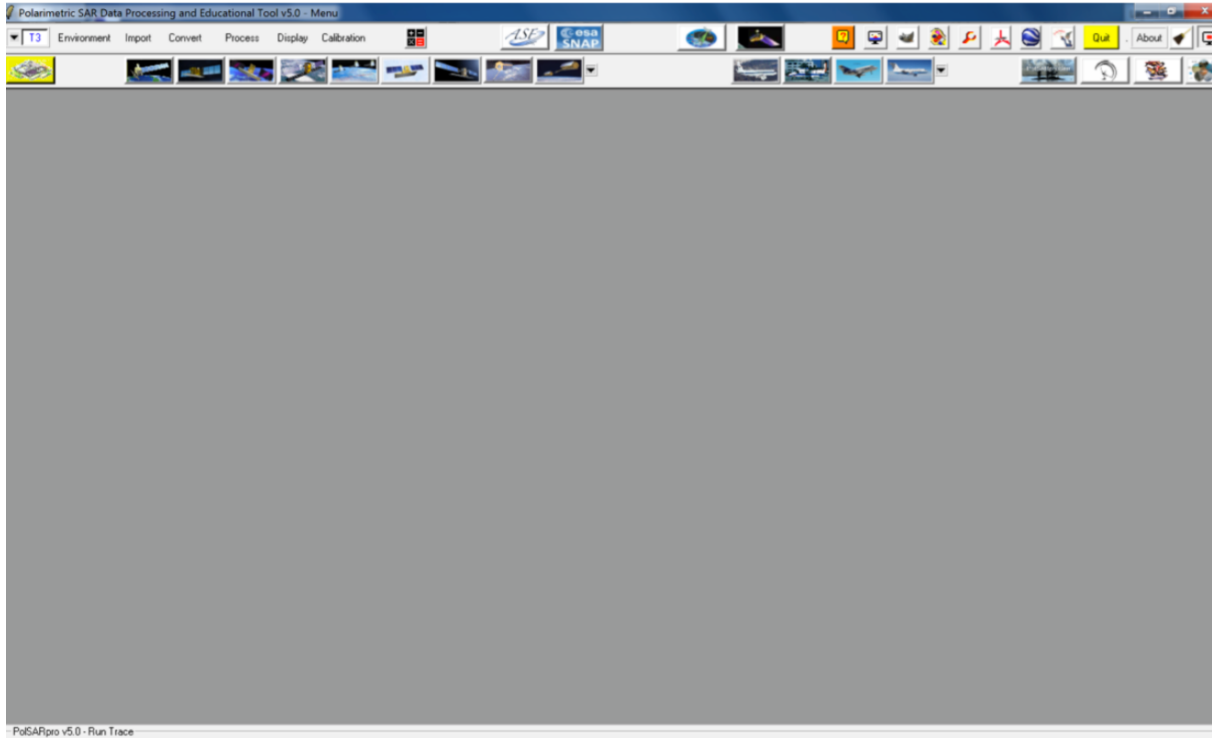
<https://earth.esa.int/web/polsarpro/download/version-5.0>



- GUI or command line
- Open source
- We will show command line routines but an example practice with GUI is here:  
[https://uavsar.jpl.nasa.gov/science/workshops/presentations2015/UAVSAR\\_Workshop2015\\_Polarimetry\\_Tutorial\\_\(Chapman\).pdf](https://uavsar.jpl.nasa.gov/science/workshops/presentations2015/UAVSAR_Workshop2015_Polarimetry_Tutorial_(Chapman).pdf)



# PolSARpro



PolSARap  
PolSARproSIM  
PolSARproSIMgr  
PolSARproSIMsv  
SVM  
basis\_change  
bmp\_process  
calculator  
calibration  
data\_convert  
data\_import  
data\_process\_dual  
data\_process\_mult  
data\_process\_sngl  
lib  
speckle\_filter  
tools

make  
quicklooks

import files from  
UAVSAR, ALOS,  
etc.

polarimetric  
decomposition,  
classification





# PolSARpro

- You can call any function with no arguments to see the expected inputs

```
#cd to directory  
Soft/data_process_sngl./wishart_h_a_  
alpha_classifier.exe
```

PolSARPro will warn you about the lack of arguments, then provide the usage

```
A processing error occurred !  
Not enough input arguments  
Usage:
```

```
wishart_h_a_alpha_classifier.exe
```

## Parameters:

(string)	-id	input directory
(string)	-od	output directory
(string)	-iodf	input-output data format
(int)	-nwr	Nwin Row
(int)	-nwc	Nwin Col
(int)	-ofr	Offset Row
(int)	-ofc	Offset Col
(int)	-fnr	Final Number of Row
(int)	-fnc	Final Number of Col
(string)	-hf	input entropy file
(string)	-af	input anisotropy file
(string)	-alf	input alpha file
(int)	-nit	maximum iteration number
(float)	-pct	maximum of pixel switching classes
(int)	-bmp	BMP flag (0/1)
(string)	-co8	input colormap8 file (valid if BMP flag = 1)
(string)	-co16	input colormap16 file (valid if BMP flag = 1)

## Optional Parameters:

(string)	-mask	mask file (valid pixels)
(int)	-mem	Allocated memory for blocksize determination (in Mb)
(string)	-errf	memory error file
(noarg)	-help	displays this message
(noarg)	-data	displays the help concerning Data Format parameter



# Ingest UAVSAR Files and Make a T3 Matrix

```
uavsar_convert_MLC.exe -hf Mondah_27080_16015_000_160308_L090_CX_02.ann\  
-if1 Mondah_27080_16015_000_160308_L090HHHH_CX_02.grd \  
-if2 Mondah_27080_16015_000_160308_L090HHHV_CX_02.grd \  
-if3 Mondah_27080_16015_000_160308_L090HHVV_CX_02.grd \  
-if4 Mondah_27080_16015_000_160308_L090HVHV_CX_02.grd \  
-if5 Mondah_27080_16015_000_160308_L090HVVV_CX_02.grd \  
-if6 Mondah_27080_16015_000_160308_L090VVVV_CX_02.grd \  
-od T3 -odf T3 -inr 3750 -inc 12618 -ofr 0 -ofc 0 -fnr 3750 -fnc 12618  
-nlr 2 -nlc 2 -ssr 1 -ssc 1
```

input rows and  
columns

taking looks

I called the output  
directory 'T3'





# H- $\alpha$ Decomposition and Classification

```
h_a_alpha_decomposition.exe -id T3 -od decomposition -iodf T3 \  
-nwr 7 -nwc 7 -ofr 0 -ofc 0 -fnr 1875 -fnc 6309 \  
-f11 0 -f12 1 -f13 1 -f14 1 -f15 0 -f16 0 -f17 0 -f18 0 -f19 0
```

-od is the output directory, I'm calling it 'decomposition'

-id is the input directory with T3 elements, I'm calling it 'T3'

-nwr and nwc is the window size used to calculate coherence (7x7)

-fnr and fnc refer to number of rows and cols from config.txt file

-lf are flags to indicate the desired output files (alpha, entropy, lambda)

```
h_a_alpha_planes_classifier.exe -id decomposition -od  
classification -ofr 0 -ofc 0 -fnr 1875 -fnc 6309 -hal 1 -han 0  
-anal 0 -clm Planes_H_A_Alpha_ColorMap9.pal
```

-od is the output directory, I'm calling it 'classification'



# Make an ENVI Header

```
ENVIDescription = { File Imported into ENVI.}
samples = 6309
lines = 1875
bands = 1
header offset = 0
file type = ENVI Standard
data type = 4
interleave = bsq
sensor type = Unknown
byte order = 0
map info = {Geographic Lat/Lon, 1.5000, 1.5000,
9.17956764, 0.60482616, 1.1112000000e-04,
1.1112000000e-04, WGS-84,
units=Degrees}coordinate system string
={GEOGCS["GCS_WGS_1984",DATUM["D_WGS_1984",SPHEROID["WGS_1984",6378137.0,298.257223563]],PRIME
M["Greenwich",0.0],UNIT["Degree",0.017453292519
9433]]}
wavelength units = Unknown
```

- From PolSARPro config.txt file:
  - Nrow
  - Ncol
- From UAVSAR annotation file:
  - Center Latitude of Upper Left Pixel of Image
  - Center Longitude of Upper Left Pixel of Image
  - Multiply GRD Latitude Pixel Spacing by 2 since we took 2 looks:  $0.00005556 * 2 = 0.0011112$



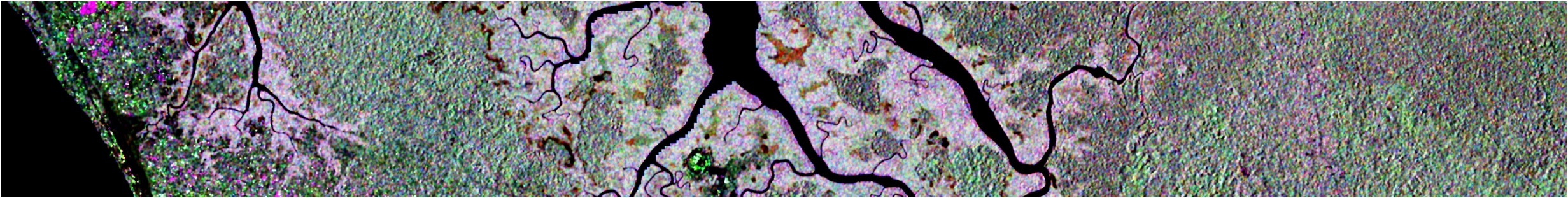




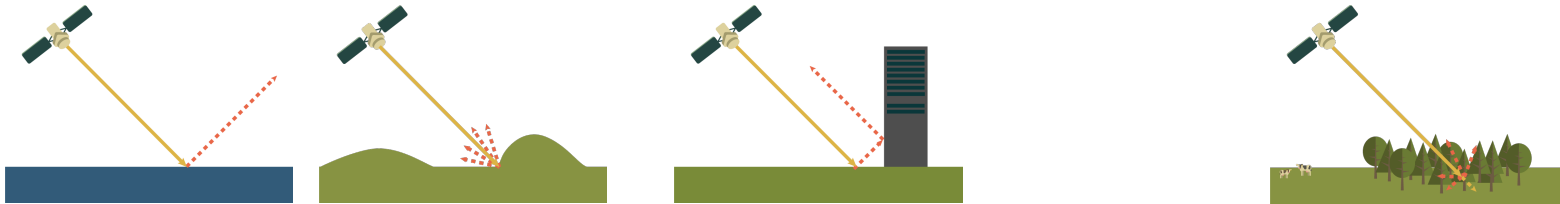
Display the Results



# Sentinel-1 Polarization Ratios



VV VH VV

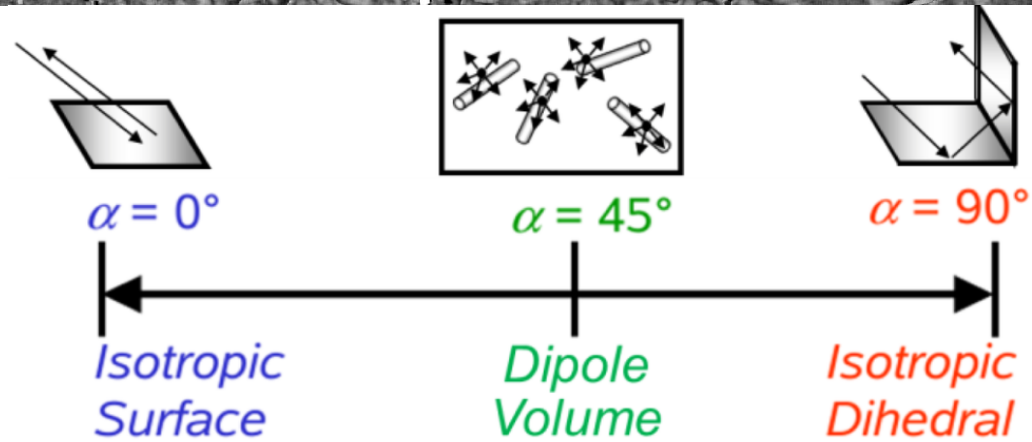
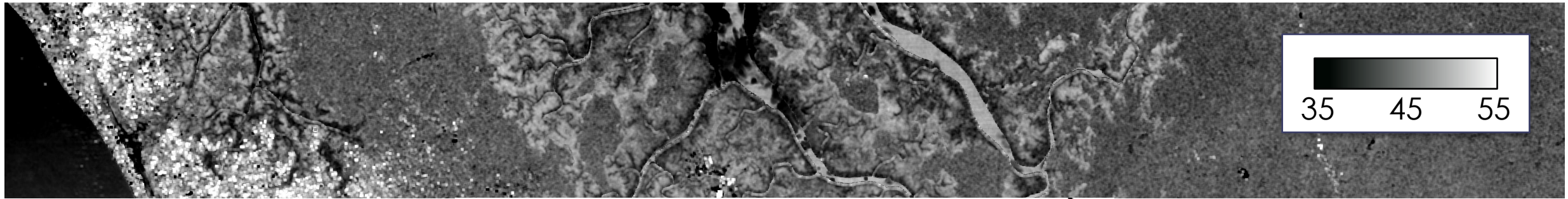


	Specular	Surface	Double Bounce	Volume	
dB	Open Water	Runway	Buildings	Forest	Tall Mangroves
VV Mar 20	-16.0	-11.7	-0.5	-4.5	-4.2
VH Mean (Mar 20, 08)	-19.5	-16.5	-13	-10.9	-11.9
VV Mar 08	-17.0	-12.6	-0.5	-5.6	-4.3





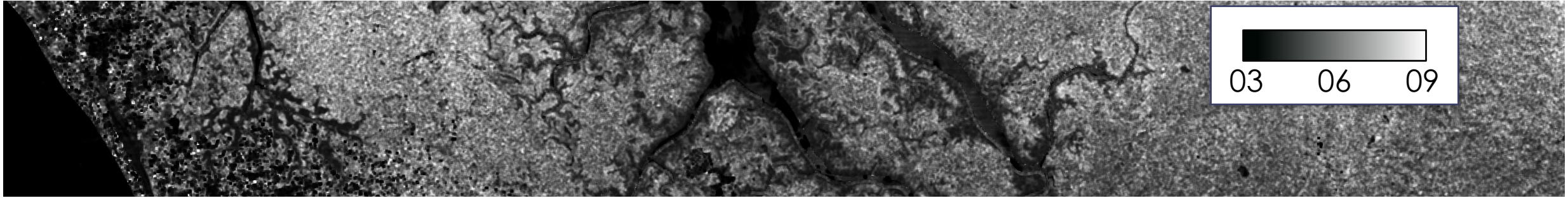
# UAV-SAR Alpha-Decomposition Results



	Open Water	Runway	Buildings	Forest	Tall Mangroves
Alpha ( $\alpha$ )	36	29	55	42	46
Entropy (H)					
Lambda					



# UAVSAR- Entropy Decomposition Results, slide 38 UAVSAR-Lambda Decomposition Results



Low Entropy

$$0 < H < 1$$

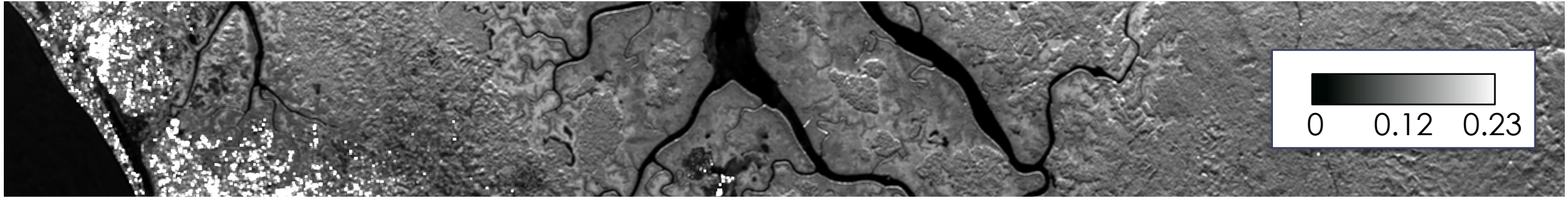
High Entropy

	Open Water	Runway	Buildings	Forest	Tall Mangroves
Alpha ( $\alpha$ )	36	29	55	42	46
Entropy (H)	0.15	0.67	0.45	0.89	0.79
Lambda					





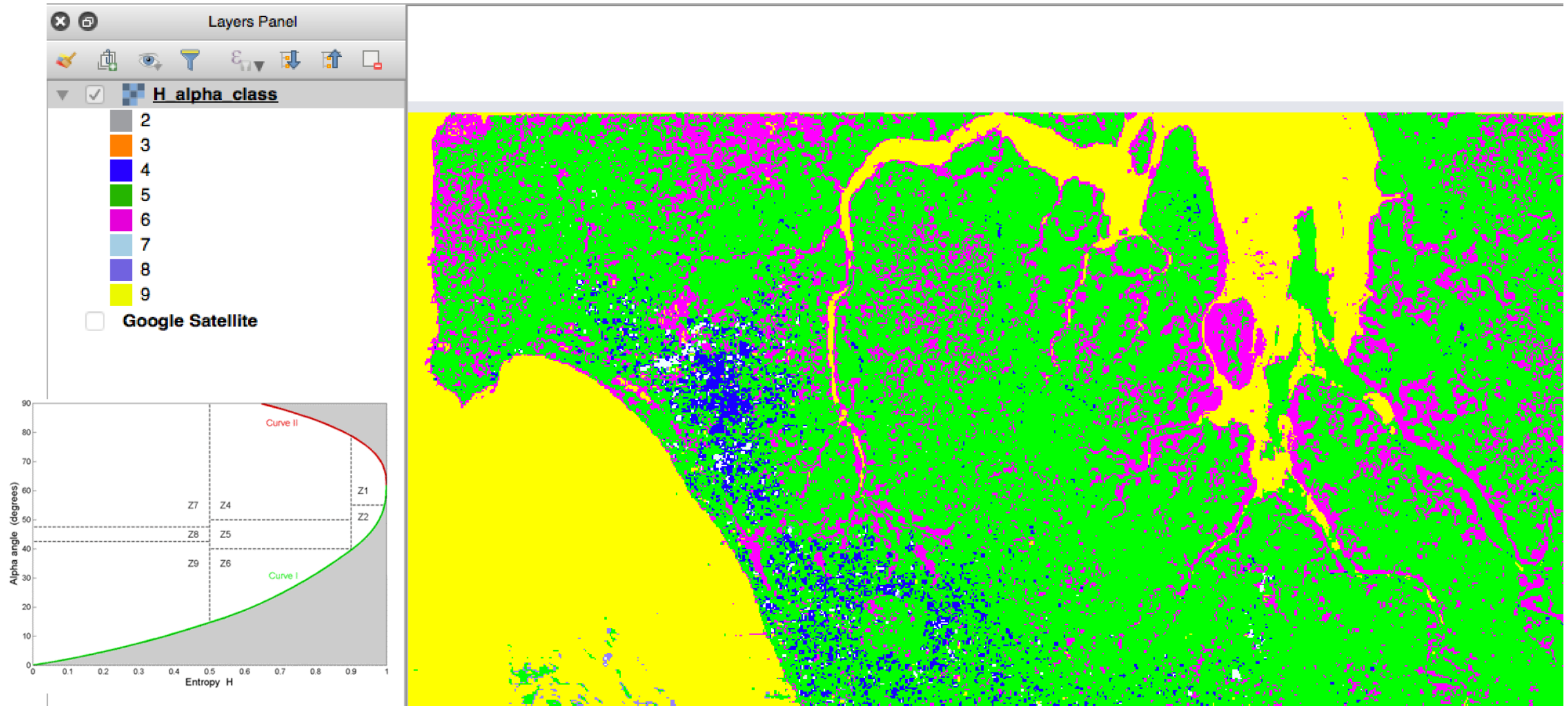
# Classification Results from Entropy and Alpha Decompositions



	Open Water	Runway	Buildings	Forest	Tall Mangroves
Alpha ( $\alpha$ )	36	29	55	42	46
Entropy (H)	0.15	0.67	0.45	0.89	0.79
Lambda	0.009	0.007	0.55	0.085	0.067



# Entropy + Alpha





# Additional Resources

- Land Remote Sensing course from the European Space Agency:
  - [http://seom.esa.int/landtraining2014/files/LTC2014\\_Programme\\_Materials.pdf](http://seom.esa.int/landtraining2014/files/LTC2014_Programme_Materials.pdf)
- Polarimetry tutorials accompanying PolSARPro:
  - <https://earth.esa.int/web/polsarpro/polarimetry-tutorial>
- Natural Resources Canada tutorial:
  - <http://www.nrcan.gc.ca/node/9579>







Thank you!